Mohamed Hafiz Week 2 FYP Report

Week 2 has been a dry and unproductive week, I spent too much time trying to code the robot to read/decode QRcode. There are very little resources on how to make NAO read/decode QRcode. When I search on YouTube and google, QRcode reading has nothing related to NAO robot, it’s possible but so far there are no open source on how to do it. I think that is beyond my capability as a student. I hope with the new task Ms. Li has given me, I can manage and at least show some results by the end of week 3.

Looking ahead I should focus on the new task which is to interact with human by touching the sensors. By touching the sensors which is located at the hands, legs and head of the robot, the robot will do different postures every time one of the sensors is touched and will reset to initial posture if the head sensor is touched.